Efficiently completing partial configurations

Toward automatically learned search heuristics for CSP-encoded configuration problems Results from an initial experimental analysis

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Background

Not all configurations are created equal

Looking for an E-series Mercedes?



Common combinations

▶ 19,219 used cars online

Customer requirement: "E-Series"

1. Make Mercedes-Benz	2. Make All →	3. Make				
Model E-Series	Model	Model <				
Version (i)						
Fuel type All Particulate filter	Transmission All	Power kW (HP) kW → from … to				
Number of seats	Doors	Car type				
from 🔹 💀 to	All	All				
Final price (€)	Mileage	First registration				
1 000 👻 •• to	from - •• to -	from 🗸 •• to 👻				

19,219 vehicles 🕨

Common combinations

▶ 16,233 (~84%) with automatic transmission

Customer requirement: "E-Series", "automatic transmission"

	Vehicle						
	1. Make Mercedes-Benz -	2. Make	3. Make				
	Model E-Series 👻	All 👻	Model All				
	Version (i)						
	Fuel type All - Particulate filter	Transmission automatic -	Power kW (HP) kW - from to				
	Number of seats	Doors	Car type				
	from 🔹 💀 to 👻	All	All				
Final price (€)		Mileage	First registration				
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16,233 vehicles >

Main hypothesis & approach

Configuration problem solving can be hard

- Configurations can comprise thousands of parameter settings
- Despite the use of high-performance solvers, domain-specific heuristics might be required for efficient problem solving

Observations:

- Some configurations are much more likely (popular) than others
- The majority of customers might have very similar requirements
 See yesterday's talk on customer demanded variety

Therefore:

- It might be good to explore the "popular" part of the search space first
- Where to search first, can be learned from past configurations

A CSP-based approach

Constraint Satisfaction

- Long tradition of modeling configuration problems as Constraint Satisfaction Problems
- Basic form, given
 - ► V set of variables with defined domains (D)
 - ► C a set of constraints on legal, simultaneous value assignments
- Find:
 - An assignment of a value to each variable in V such that all constraints from C are satisfied

Advanced CSP models

- Partially based on requirements from the configuration domain
 - Dynamic CSPs some variables are only relevant in certain situations
 - □ Generative CSPs variables can be added dynamically to the problem

In this work

Goal

 Demonstrate the general plausibility and feasibility of a learning-based approach

What has been done?

- A simulation-based experiment using CSP benchmark problems
- Compare problem solving time for different search (branching) heuristics
 - A) Default strategy of the solver
 - B) A learning-based strategy that uses statistics about previous successful configurations
 - Idea: If the user chose an E-Series model, try the option "automatic transmission" before the "manual" transmission. (even simpler, in fact)

Protocol details

I. Find a set of suitable CSP benchmark problems

- Used CSP problems from the CP'08 solver competition
- Both standard problems (N-Queens) and a true configuration problem (Renault)
- Problems should be easily solvable (below I sec)

2. Simulate configuration problem instances for learning

- Determine some variables to be input variables
 e.g., 5 variables with domain size 10 (leading to 1000 possible inputs)
- Search for valid solutions given some random or biased inputs
 Record the solutions using the default strategy
- 3. Learn a good strategy (a trivial one in our case)
- 4. Re-solve the same problems using the learned strategy
- 5. Compare the running times

Statistics-based search space exploration

Simple learning strategy applied as proof-of-concept

- When "trying out" different value assignments, try the one that was part of the most solutions so far
 - Not depending on inputs
 - Not depending on other variable assignments
- More advanced strategies are of course possible
 - Make choice dependent on other assignments so far
 - Learn more complex rules,
 - □ e.g., based on Association Rule Mining
 - > Perform a static analysis, induce additional "constraints"

Technically – Adapt the branching strategy



- Standard
 backtracking
- Constraint propagation omitted here

Choice points – Variables and Values

Two decision points:

- Which variable to try next?
 - e.g., based on Fail-First principle (minimum domain)
- Which value to try first?
 - e.g., based on the order (increasing domain)

Choice strategy depends on problem structure

- Solving a standard benchmark with Choco (Java-based solver)
 - Default strategy:
 I minute (!)
 - Impact-based branching: 800ms
 - Increasing domain: 500ms
 - Decreasing domain: 30ms

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Statistics-based branching

- Implementation of a trivial "ValueSelection" class
 - Extension mechanism of Java-based constraint solver Choco used
 - Strategy is based on a static ordering of values for each variable determined in the learning phase
 - If no ordering exists or some values were never part of a solution, use a typical default strategy (Increasing Domain)

More protocol details

- For each benchmark problem ...
- Statistics collection phase
 - Randomly determine "input" variables
 - For (i = I to 300)

Create random inputs using Gaussian distribution as not all inputs are equally frequent

Search for a solution

IF solution exists

increase the "successful value" counters for the variables

remember the required solution time

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IF (i = 30 or i = 50 or ... i = 300)
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save a snapshot of the statistics so far

Results:

□ Average running times with default strategy (300 runs)

□ Statistics of the form VI = [4,2,3,5,1], V2 = [3,2,4,1,5]

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More protocol details

- Measuring the effects (for each benchmark problem)
 - For each snapshot (30, 50, 100, 150, 200, 300)

For (i = I to 300)

Create random input values for the input variables used in the collection phase; do not use exact same inputs (solution caching)

Search for a solution

If solution exists

record the required running times

Results

Required running times for different learning levels

Measurements (CPU time): initial results

	Problem name	Default	30	50	100	150	200	300	Diff.
1	normalized-renault-mod-0_ext.xml	143,44	37,03	26,20	26,60	28,72	28,70	30,77	-82%
2	normalized-bibd-8-14-7-4-3_glb.xml	11,71	7,65	6,94	7,71	7,64	8,38	6,48	-41%
3	normalized-squares-9-9.xml	53,75	41,88	44,30	41,72	42,40	43,32	44,90	-22%
4	normalized-geo50-20-d4-75-29_ext.xml (less inputs)	431,25	353,07	366,06	327,03	354,16	342,25	352,29	-24%
5	normalized-geo50-20-d4-75-24_ext.xml	95,11	99,64	91,66	87,19	93,27	100,32	99,39	-8%
6	normalized-costasArray-13.xml	53,36	48,33	47,70	47,18	47,13	46,96	46,49	-12%
7	normalized-air05.xml	856,51	847,22	859,04	850,81	854,80	848,71	853,36	-1%
8	normalized-magicSquare-5_glb.xml (GAUSSIAN)	112,59	142,86	149,65	145,17	140,57	147,66	145,05	25%
9	normalized-magicSquare-5_glb.xml (RANDOM)	122,81	154,49	144,64	137,90	141,06	131,88	139,49	7%

- Strongest effect on real configuration problem
 - III variables, average domain size = 5, 6 input variables, > 15.000 poss. input comb.
 - ▶ up to 82% decrease in search times
- Good effect also on other problems
- Running times can slightly increase again when more data exist
 - No statistical significance tests made so far
- Results get worse when problem structure is symmetric
 - Magic squares (e.g., assign each number from 1 to 9 on a 3-by-3 field)
 - Also experimented with using uniform distribution

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Observations

- Already trivial strategies can lead to significant reductions in search time
 - Assumption is a non-uniform distribution of customer requirements / configurations
 - Achievable improvements depend on the problem structure
- Looking at standard deviations (Renault problem)
 - Default strategy: 220ms, Statistics-based strategy: around 110ms
 - Standard deviation also gets lower
 - □ But is larger when compared to overall running times
 - Interpretation
 - □ Statistics-based search in many cases very fast
 - But there are more cases where the solver is guided to wrong area of search space

Previous works

Not many papers found

Pointers to corresponding literature welcome

"Online learning" approaches

- Try to adapt the strategy during one search process
 - e.g., determining the likelihood of the existence of at least one solution in the search graph to be explored
 - $\hfill\square$ based on static analysis and simplification of the graph

In Answer Set Programming

Learning a "policy" based on past solution runs

On other domains

Instruction scheduling on modern processors

Summary & Future works

In product configuration,

- problems are solved many times
- solutions are not uniformly distributed in the search space

Our proposal

Learn from past solver runs to find solutions more quickly

Experiments

- Conducted experiments with benchmark problems and a trivial value selection strategy
- Results indicate the general feasibility

Future work

- Use more advanced strategies
- However: consider cost of strategy application at run time

Announcement

- Upcoming Dagstuhl seminar on unifying Software and Product configuration
 - To take place in April 2014
 - Commonalities and differences
 - Feature models vs. configuration models, expressivity, reasoning, reinventing the wheel
 - http://www.dagstuhl.de/14172

See also

Arnaud Hubaux, Dietmar Jannach, Conrad Drescher, Leonardo Murta, Tomi Mannistö Krzysztof Czarnecki, Patrick Heymans, Tien Nguyen and Markus Zanker. Unifying Software and Product Configuration: A Research Roadmap. Configuration Workshop 2012 Thank you for your attention! Questions?